



Some Fixed Point and Common Fixed Point Results in L-Space with Rational Contraction

Animesh Gupta*, Dilip Jaiswal** and S.S. Rajput***

*Department of Mathematics, Government Benazir Science and Commerce College, Bhopal, (MP)

**Department of Mathematics, Moti Lal Vigyan Mahavidhyalaya, Bhopal, (MP)

*** Department of Mathematics, Government P.G. College, Gadarwara, (MP)

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ABSTRACT : There are several Theorems are prove in L-space, using various type of mappings. In this paper, we prove some fixed point theorem and common fixed point. Theorems, in L-space using different, symmetric rational mappings.

Keywords: Fixed point, Common Fixed point, L-space, Continuous Mapping, Self Mapping, Weakly Compatible Mappings. 2000 Mathematics Subject Classification: 47H10, 54H25.

I. INTRODUCTION

It was shown by S. Kasahara [13] in 1976, that several known generalization of the Banach Contraction Theorem can be derived easily from a Fixed Point Theorem in an L-space. Iseki [10] has used the fundamental idea of Kasahara to investigate the generalization of some known Fixed Point Theorem in L-space.

Let N be the set of natural numbers and X be a nonempty set. Then L-space is defined to be the pair (X, \rightarrow) of the set X and a subset \rightarrow of the set $X^N \times X$, satisfying the following conditions:

L_1 - if $x_n \rightarrow x \in X$ for all $n \in N$, then $(\{x_n\}_{n \in N}, x) \in \rightarrow$

L_2 - if $(\{x_n\}_{n \in N}, x) \in \rightarrow$, then $(\{x_{n_i}\}_{i \in N}, x) \in \rightarrow$

For every subsequence $\{x_{n_i}\}_{i \in N}$ of $\{x_n\}_{n \in N}$

In what follows instead of writing $(\{x_n\}_{n \in N}, x) \in \rightarrow$, we write $\{x_n\}_{n \in N} \rightarrow x$ or $x_n \rightarrow x$ and read $\{x_n\}_{n \in N}$ converges to x . Further we give some definitions regarding L-space.

Definition 1. Let (X, \rightarrow) be an L-space. It is said to be 'separated' if each sequence in x converges to at most one point of X .

Definition 2. A mapping f on (X, \rightarrow) into an L-space (X', \rightarrow') is said to be 'continuous' if $x_n \rightarrow x$ implies $f(x_{n_i}) \rightarrow' f(x)$ for some subsequence $\{x_{n_i}\}_{i \in N}$ for $\{x_n\}_{n \in N}$.

Definition 3. Let d - be a non negative extended real valued function on $X \times X$: $0 \leq d(x, y) \leq \infty_i$ for all $x, y \in X$. The L-space is said to be d - complete if each sequence $\{x_n\}_{n \in N}$ in X with $\sum_{i=0}^{\infty} d(x_i, x_{i+1}) < \infty$ converges to the atmost one point of X .

In this context Kasahara S. proved a lemma, which as follows:

Lemma (S. Kasahara):

Let (X, \rightarrow) be an L-space which is d - complete for a non negative real valued function d on $X \times X$. If (X, \rightarrow) is separated then:

$d(x, y) = d(y, x) = 0$ implies, $x = y$ for all $x, y \in X$

During the past few years many great mathematicians Yeh [19], Singh [18], Pathak and Dubey [14], Sharma and Agrawa [17], Patel, Sahu and Sao [15], Patel and Patel [16], worked for L-space. In this chapter, we similar investigation for the study of Fixed Point Theorems in L-space are worked out. We find some more Fixed Point Theorem and Common Fixed Point Theorem in L-sapce.

Theorem 1

Let (X, \rightarrow) be a separated L-space, which is d - complete for a non negative real valued function d on $X \times X$ with $d(x, x) = 0$, for each x in X . Let E, F and T be three continuous self mapping of X into itself, satisfying the following condition:

$1c_1 : E(X) \subset T(X)$

and $F(X) \subset T(X)$, $ET - TE, FT = TF$

$$1c_2: d(Ex, Fy) \leq \alpha \left[\frac{d(Tx, Ty)\{d(Tx, Ex) + d(Ty, Fy)\}}{d(Tx, Fy) + d(Ty, Ex)} \right] + \beta[d(Tx, Ex) + d(Ty, Fy)] + \gamma[d(Tx, Fy) + d(Ty, Ex)] + \delta.d(Tx, Ty)$$

For all x, y in X , where non negative $\alpha, \beta, \gamma, \delta$ such that $0 \leq \alpha + \beta + \gamma + \delta < 1$, with $Tx \neq Ty$. Then E, F, T have unique common fixed point.

Proof:

Let $x_0 \in X$, since $E(X) \subset T(X)$ we can choose a point $x_1 \in X$, such that $Tx_1 = Ex_0$, also $F(X) \subset T(X)$, we can choose $x_2 \in X$ such that $Tx_2 = Fx_1$. In general we can choose the point:

$$Tx_{2n+1} = Ex_{2n} \quad \dots (1.1)$$

$$Tx_{2n+2} = Fx_{2n+1} \quad \dots (1.2)$$

Now consider,

$$d(Tx_{2n+1}, Tx_{2n+2}) = d(Ex_{2n}, Fx_{2n+1})$$

From $1c_2$

$$d(Tx_{2n}, Fx_{2n+1}) \leq \alpha \left[\frac{d(Tx_{2n+1})\{d(Tx_{2n}, Ex_{2n}) + d(Tx_{2n+1}, Fx_{2n+1})\}}{d(Tx_{2n}, Fx_{2n+1}) + d(Tx_{2n+1}, Ex_{2n})} \right] \\ + \beta[d(Tx_{2n}, Ex_{2n}) + d(Tx_{2n+1}, Fx_{2n+1})] \\ + \gamma[d(Tx_{2n}, Fx_{2n+1}) + d(Tx_{2n+1}, Ex_{2n})] \\ + \delta.d(Tx_{2n}, Tx_{2n+1})$$

$$d(Tx_{2n+1}, Tx_{2n+2}) \leq \alpha \left[\frac{d(Tx_{2n}, Tx_{2n+1})\{d(Tx_{2n}, Tx_{2n+1}) + d(Tx_{2n+1}, Tx_{2n+2})\}}{d(Tx_{2n}, Tx_{2n+2}) + d(Tx_{2n+1}, Tx_{2n})} \right] \\ + \beta[d(Tx_{2n}, Tx_{2n+1}) + d(Tx_{2n+1}, Tx_{2n+2})] \\ + \gamma[d(Tx_{2n}, Tx_{2n+2}) + d(Tx_{2n+1}, Tx_{2n+1})] \\ + \delta.d(Tx_{2n}, Tx_{2n+1})$$

$$d(Tx_{2n+1}, Tx_{2n+2}) \leq \left[\frac{\alpha + \beta + \gamma + \delta}{1 - \beta - \gamma} \right] d(Tx_{2n}, Tx_{2n+1})$$

$$d(Tx_{2n+1}, Tx_{2n+2}) \leq q.d(Tx_{2n}, Tx_{2n+1})$$

$$\text{where } q = \left[\frac{\alpha + \beta + \gamma + \delta}{1 - \beta - \gamma} \right] < 1;$$

For $n = 1, 2, 3, \dots$

Whether, $d(Tx_{2n+1}, Tx_{2n+2}) = 0$ or not

Similarly, we have

$$d(Tx_{2n+1}, Tx_{2n+2}) \leq q^n.d(Tx_0, Tx_1)$$

For every positive integer n , this means that,

$$\sum_{i=0}^{\infty} d(Tx_{2i+1}, Tx_{2i+2}) < \infty$$

Thus the d - completeness of the space implies that, the sequence $(T^n x_0)_{n \in \mathbb{N}}$ converges to some u in X . so by (1.1) and (1.2):

$\{E^n x_0\}_{n \in \mathbb{N}}$ and $\{F^n x_0\}_{n \in \mathbb{N}}$ also converges to the some point u , respectively.

Since E, F, T are continuous, there is a subsequence t of $\{T^n x_0\}_{n \in \mathbb{N}}$ such that:

$$E[T(t)] \rightarrow E(u), T[E(t)] \rightarrow T(u), F[T(t)] \rightarrow F(u),$$

$$T[F(t)] \rightarrow T(u)$$

$$\text{By } (1c_1) \text{ we have, } E(u) = F(u) = T(u) \quad \dots (1.3)$$

Thus, we can write

$$T(Tu) = T(Eu) = E(Tu) = E(Eu) = E(Fu) = T(Fu) = F(Tu) \\ = F(Eu) = F(Fu) \quad \dots (1.4)$$

By $1c_2$, (1.3) and (1.4) we have, if $E(u) \neq F(Eu)$

$$d[Eu, F(Eu)] \leq \alpha \left[\frac{d[Tu, T(Eu)]\{d(Tu, Eu) + d\{T(Eu), F(Eu)\}\}}{d[Tu, F(Eu)] + d\{T(Eu), Eu\}} \right] \\ + \beta[d(Tu, Eu) + d\{T(Eu), F(Eu)\}] \\ + \gamma[d\{Tu, F(Eu)\} + d\{T(Eu), Eu\}] \\ + \delta.d[Tu, T(Eu)] \\ d[Eu, F(Eu)] \leq (\beta + \gamma + \delta).d[Eu, F(Eu)]$$

Thus we get a contradiction,

$$\text{Hence } Eu = F(Eu) \quad \dots (1.5)$$

From (1.4) and (1.5) we have

$$Eu = F(Eu) = T(Eu) = E(Eu)$$

Hence Eu is a common fixed point of E, F and T .

Uniqueness:

Let v is another fixed point of E, F and T different from u , then by $1c_2$ we have:

$$d(u, v) = d(Eu, Fv)$$

$$d(Eu, Fv) \leq \alpha \left[\frac{d(Tu, Tv)\{d(Tu, Eu) + d(Tv, Fv)\}}{d(Tu, Fv) + d(Tv, Eu)} \right]$$

$$+ \beta[d(Tu, Eu) + d(Tv, Fv)] \\ + \gamma[d(Tu, Fv) + d(Tv, Eu)] \\ + \delta.d(Tu, Tv)$$

$$d(u, v) \leq (2\gamma + \delta).d(u, v)$$

Which contradiction.

Therefore u is unique fixed point of E, F and T in X .

Remark:

I. If we put $\alpha = \beta = \gamma = 0$ then we get result of Jungck [11] in Lspace.

II. If we put $\alpha = \gamma = \delta = 0$ then we get the result of Kannan [12] in L-space.

III. If we put $\alpha = \gamma = 0$ then we get the result of Chatterjee [5] in L-space.

Theorem 2

Let (X, \rightarrow) be a separated L-space, which is d - complete for a non Negative real valued function d on $X \times X$ with $d(x, x) = 0$, for each x in X . Let E, F and T be three continuous self mapping of X into itself, satisfying the following condition:

$$2c_1: \quad E(X) \subset T(X) \text{ and } F(X) \subset T(X)$$

$$ET = TE, FT = TF$$

$$2c_2: \quad d(E^r x, F^s y) \leq \alpha \left[\frac{d(Tx, Ty)\{d(TxE^r x) + d(TyF^s y)\}}{d(TxF^s y) + d(TyE^r x)} \right]$$

$$\begin{aligned} & +\beta[d(Tx, E^r x) + d(Ty, F^s y)] \\ & +\gamma[d(Tx, F^s y) + d(Ty, E^r x)] \\ & +\delta.d(Tx, Ty) \end{aligned}$$

For all x, y in X , where non negative $\alpha, \beta, \gamma, \delta$ such that $0 \leq \alpha + \beta + \gamma + \delta < 1$ with $Tx \neq Ty$. If some positive integers r, s exists such that E^r, F^s and T are continuous. Then E, F, T have unique common fixed point.

Proof:

We have

$$\begin{aligned} E(X) \subset T(X) \text{ and } F(X) \subset T(X) \\ ET = TE, FT = TF \end{aligned}$$

It follows that:

$$\begin{aligned} E^r(X) \subset T(X) \text{ and } F^s(X) \subset T(X) \\ E^r T = TE^r, F^s T = TF^s \end{aligned}$$

By theorem (1), there is a unique fixed point in X such that,

$$u = Tu = E^r u = F^s u \quad \dots (2.1)$$

i.e u is the unique fixed point of T, E^r and F^s

$$\text{Now } T(Eu) = E(Tu) = Eu = E(E^r u) = E^r(EU) \quad \dots (2.2)$$

$$\text{And } T(Fu) = F(Tu) = Fu = F(F^s u) = F^s(Fu) \quad \dots (2.3)$$

Hence it follows that Eu is a common fixed point of E^r and T , similarly is Fu a common fixed point of T and F^s in X . The uniqueness of u from (2.1), (2.2) and (2.3) implies that:

$$u = Eu = Fu = Tu$$

This complete the proof of the theorem.

Remark:

(i) If $r = s = 1$ then we get Theorem 1.

Theorem 3

Let (X, \rightarrow) be a separated L-space, which is d -complete for a non negative real valued function d on $X \times X$ with $d(x, x) = 0$, for each x in X . Let A, B, S and T be continuous self mapping of X into itself, satisfying the following condition:

$$\begin{aligned} 3c_1: \quad A(X) \subseteq T(X) \text{ and } B(X) \subseteq T(X) \text{ as } SA \\ BT = TB \text{ and } T(X) \text{ or } S(X) \text{ are closed sub set of } X \end{aligned}$$

$$3c_2: \quad d(Ax, By) \leq \alpha d(Sx, Ty) + \beta_{\max} [d(Sx, Ax), d(Ty, By), d(Sx, By), d(Ty, Ax)]$$

For all x, y in X , where non negative such that $0 \leq \alpha + \beta < 1$, then A, B, S, T have unique common fixed point in X .

Proof:

Let x_0 be an arbitrary point of X , since $A(X) \subseteq T(X)$ we can choose the point x_1 and y_0 in X such that,

$$Ax_0 = Tx_1 = y_0$$

Also $B(X) \subseteq S(X)$, we can choose the point x_2 and y_1 in X such that,

$$Bx_1 = Sx_2 = y_1$$

In general we can choose the points

$$Tx_{2n+1} = Ax_{2n} = y_{2n} \quad \dots (3.1)$$

$$\text{And } Sx_{2n+2} = B_{2n+1} = y_{2n+1} \quad \dots (3.2)$$

For all $n = 0, 1, 2, \dots \dots \dots$

Now consider,

$$d(y_{2n}, y_{2n+1}) = d(Ax_{2n}, Bx_{2n+1})$$

From $3c_2$:

$$\begin{aligned} d(Ax_{2n}, Bx_{2n+1}) & \leq \alpha d(Sx_{2n}, Tx_{2n+1}) + \\ & \beta_{\max} \left[d(Sx_{2n}, Ax_{2n}), d(Tx_{2n+1}, Bx_{2n+1}) \right] \\ d(y_{2n}, y_{2n+1}) & \leq \alpha d(y_{2n-1}, y_{2n}) + \\ & \beta_{\max} \left[d(y_{2n}, y_{2n-1}), d(y_{2n}, y_{2n+1}) \right] \dots (3.3) \end{aligned}$$

There arise three cases,

Case 1

If we take max is $d(y_{2n-1}, y_{2n})$, then (3.3) gives,

$$d(y_{2n+1}, y_{2n}) \leq (\alpha + \beta)d(y_{2n-1}, y_{2n})$$

Case 2

If we take max is $d(y_{2n+1}, y_{2n})$, then (3.3) gives

$$d(y_{2n+1}, y_{2n}) \leq \frac{\alpha}{1-\beta} d(y_{2n-1}, y_{2n})$$

Case 3

If we take max is $d(y_{2n+1}, y_{2n-1})$, then (3.3) gives

$$d(y_{2n+1}, y_{2n}) \leq \frac{\alpha + \beta}{1 - \beta} d(y_{2n-1}, y_{2n})$$

From the above Cases 1, 2, 3, we observe that,

$$d(y_{2n+1}, y_{2n}) \leq qd(y_{2n-1}, y_{2n})$$

$$\text{where } q = \max \left[(\alpha + \beta), \frac{\alpha}{1-\beta}, \frac{\alpha + \beta}{1-\beta} \right] < 1$$

For $n = 1, 2, 3, \dots \dots \dots$

Similarly we have,

$$d(y_{2n+1}, y_{2n}) \leq q^n d(y_0, y_1)$$

For every positive integer n , this means that,

$$\sum_{i=0}^{\infty} d(y_{2i+1}, y_{2i}) < \infty$$

Thus the completeness of the space implies that the sequence $\{y_n\}_{n \in \mathbb{N}}$ converges to the some u in X so by

(3.1) and (3.2) the sequence $\{A^n x_0\}$, $\{B^n x_0\}$, $\{S^n x_0\}$, $\{T^n x_0\}$ also converges to the some points u respectively:

Since A, B, S, T are continuous, this implies

$$Tx_{2n+1} = Ax_{2n} = y_{2n} \rightarrow u \text{ as } n \rightarrow \infty$$

$$Sx_{2n+2} = B_{2n+1} = y_{2n+1} \rightarrow u \text{ as } n \rightarrow \infty$$

The pair (A, S) and (B, T) are weakly compatible which gives that, U is a common fixed point of A, B, S and T .

Uniqueness:

Let us assume that w is another fixed point of A, B, S, T in X different form u , i.e. $u \neq w$ then

$$Tu = Au = u \text{ and } Sw = Bw = w$$

From $3c_2$ we have,

$$d(u, w) < (\alpha + \beta) d(u, w)$$

Which contradiction.

Hence u is a unique common fixed point of A, B, S, T in X .

This complete the proof of the theorem.

Theorem 4

Let (X, \rightarrow) be a separated L-space, which is d - complete for a non negative real valued function d on $X \times X$ with $d(x, x) = 0$, for each x in X .

Let E, F and T be three continuous self mapping of X into itself, satisfying the following condition:

$$4c_1: \quad E(X) \subset T(X) \text{ and } F(X) \subset T(X)$$

$$ET = TE, FT = TF$$

$$4c_2: \quad \{d(Ex, Fy)\}^2 \leq \alpha d(Tx, Ex)d(Ty, Fy)$$

$$+\beta d(Tx, Fy)d(Ty, Ex)$$

$$+\gamma d(Tx, Ex)d(Ex, Ty) + \delta d(Tx, Ty)d(Ty, Fy)$$

For all x, y in X , where non negative $\alpha, \beta, \gamma, \delta$ such that $0 \leq \alpha + \beta + \gamma + \delta < 1$, with $Tx \neq Ty$ then E, F, T have unique common fixed point.

Proof:

Let $x_0 \in X$, since $E(X) \subset T(X)$ we can choose a point $x_1 \in X$, such that $Tx_1 = Ex_0$, also $F(X) \subset T(X)$, we can choose $x_2 \in X$ such that $Tx_2 = Fx_1$.

In general we can choose the point:

$$Tx_{2n+1} = Ex_{2n} \quad \dots (4.1)$$

$$Tx_{2n+2} = Fx_{2n+1} \quad \dots (4.2)$$

For every $n \in N$, we have

$$[d(Tx_{2n+1}, Tx_{2n+2})]^2 = [d(Ex_{2n}, Fx_{2n+1})]^2$$

From $5c_2$

$$[d(Ex_{2n}, Fx_{2n+1})]^2 \leq \alpha d(Tx_{2n}, Ex_{2n})d(Tx_{2n+1}, Fx_{2n+1})$$

$$+\beta d(Tx_{2n}, Fx_{2n+1})d(Tx_{2n+1}, Ex_{2n})$$

$$+\gamma d(Tx_{2n}, Ex_{2n})d(Ex_{2n}, Tx_{2n+1})$$

$$+\delta d(Tx_{2n}, Tx_{2n+1})d(Tx_{2n+1}, Fx_{2n+1})$$

$$[d(Tx_{2n+1}, Tx_{2n+2})]^2 \leq \alpha d(Tx_{2n}, Tx_{2n+1})d(Tx_{2n+1}, Tx_{2n+2})$$

$$+\beta d(Tx_{2n}, Tx_{2n+2})d(Tx_{2n+1}, Tx_{2n+1})$$

$$+\gamma d(Tx_{2n}, Tx_{2n+1})d(Tx_{2n+1}, Tx_{2n+1})$$

$$+\delta d(Tx_{2n}, Tx_{2n+1})d(Tx_{2n+1}, Tx_{2n+2})$$

$$d(Tx_{2n+1}, Tx_{2n+2}) \leq (\alpha + \delta)d(Tx_{2n}, Tx_{2n+1})$$

For $n = 1, 2, 3, \dots \dots \dots$

Whether $d(Tx_{2n+1}, Tx_{2n+2}) = 0$ or not

Similarly, we have

$$d(Tx_{2n+1}, Tx_{2n+2}) \leq (\alpha + \delta)^n d(Tx_0, Tx_1)$$

For every positive integer n , this means that,

$$\sum_{i=0}^{\infty} d(Tx_{2i+1}, Tx_{2i+2}) < \infty$$

Thus the d - completeness of the space implies that, the sequence $\{T^n x_0\}_{n \in N}$ converges to some u by (4.1) and (4.2):

$\{E^n x_0\}_{n \in N}$ and $\{F^n x_0\}_{n \in N}$ also converges to the some point respectively.

Since E, F, T are continuous, there is a subsequence t of $\{T^n x_0\}_{n \in N}$ such that,

$$E[T(t)] \rightarrow E(u), T[E(t)] \rightarrow T(u)$$

$$F[T(t)] \rightarrow F(u), T[F(t)] \rightarrow T(u)$$

By $(4c_1)$ we have,

$$E(u) = F(u) = T(u) \quad \dots (4.3)$$

Thus,

$$\begin{aligned} T(Tu) &= T(Eu) = E(Tu) = E(Eu) = E(Fu) \\ &= T(Fu) = F(Tu) = F(Eu) = F(Fu) \quad \dots (4.4) \end{aligned}$$

By $4c_2$, (4.3) and (4.4) we have,

$$E(u) \neq F(Eu)$$

$$[d\{Eu, F(Eu)\}]^2 \leq \alpha d(Tu, Eu)d[\{T(Eu), F(Eu)\}]$$

$$+\beta d[Tu, F(Eu)]d[T(Eu), Eu]$$

$$+\gamma d(Tu, Eu)d[Eu, T(Eu)]$$

$$+\delta d[Tu, T(Eu)]d[Tu, F(Eu)]$$

$$d[Eu, F(Eu)] \leq 0$$

Thus we get a contradiction.

$$\text{Hence } Eu = F(Eu) \quad \dots (4.5)$$

From (4.4) and (4.5) we have

$$Eu = F(Eu) = T(Eu) = E(Eu)$$

Hence Eu is a common fixed point of E , F and T .

Uniqueness:

Let v is another fixed point of E , F and T different from then by $1c_2$ we have,

$$\begin{aligned} [d(u, v)]^2 &= [d(Eu, Fv)]^2 \\ [d(Eu, Fv)]^2 &\leq \alpha d(Tu, Eu)d(Tv, Fv) \\ &+ \beta d(Tu, Fv)d(Tv, Eu) \\ &+ \gamma d(Tu, Eu)d(Eu, Tv) \\ &+ \delta d(Tu, Tv)d(Tv, Fv) \\ d(u, v) &\leq \beta d(u, v) \end{aligned}$$

Which contradiction.

Therefore u is unique fixed point of E , F and T in X .

Remarks:

(i) If we put $\alpha = \gamma = \delta = 0$ and $E = F$ then we get the result of Jungck [11].

(ii) If we put $\gamma = \delta = 0$ then we get the result of Pathak and Dubey [14].

(iii) If we put $\gamma = \delta = 0$ and $E = F$ then we get the result of Yeh [19].

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